

Game Analysis & Strategic Design

Team 1732

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Disclaimer

This isn't a step-by-step process. It's more like some tips with some structure in a general order?

Some stuff works for us but won't work for you. And vice versa.



Agenda

- Step Zero
 - Team Goals
 - Team Capabilities
- Strategic Design
 - Game Analysis
 - Design Selection
- Example Season





Step Zero: Team Goals

What do you want to achieve?

- Make SMART goals
- Examples:
 - Have a working robot in every match
 - Score a number of points per match
 - Play in eliminations (Be picked)
 - Be an alliance captain
 - $\circ \qquad {\sf Win \ a \ competition}$
- These goals will frame discussion about your robot design





Step Zero: Team Capabilities

- Assess your team capabilities and constraints honestly and realistically
 - Experience, machining access, budget, time, team size
 - How many people / groups can work at the same time vs. in sequence?
 - \circ ~ Even if you can build it, can you control it? Can you drive it?
- Account for scope and complexity
 - Several simple tasks will take the same or less time than a complex task



Step Zero: "Robot Points" Concept

- Let's say each team has a number of "Robot Points" to spend
 - Higher resource teams will have more Robot Points:
 - Low resource <20 Points
 - Moderate Resource 21-50 Points
 - High resource 50+ Points
- Spend points to maximize resources
 - If you have 30 Robot Points, it's better to have 3 functions at 10/10 instead of 5 at 6/10
- "Points" could mean
 - Money, machining time, person-hours

- Examples
 - Drivetrain
 - KoP Drive 2
 - 6 Wheel West Coast 6
 - Swerve 10
 - D Intake
 - Human Loaded 2
 - Ground Pickup 6
 - End game
 - Park 0
 - Climb 6
 - Autonomous routine
 - Drive forward 1
 - Complex scoring 10
- Note:
 - These point values are made up, but you get the idea

Game Analysis



Game Analysis: The Rules

- Read the manual
 - This will show the limits of what can be done in the game
- Read the manual
 - This should eliminate illegal game strategy ideas
- Read the manual
 - You may find loopholes or chokehold strategies
- Read the manual
 - The manual will be updated some ideas may become illegal
- Read the manual
 - And the Q&A



Game Analysis: Scoring Breakdown

- Read the game summary and scoring details from the Game Manual
 - (The game video can be helpful, but is occasionally misleading)
- List every way to score points
 - High goal, low goal, drive to a zone, etc.
- What's the high score?
- How does the ranking system work?
 - FRC loves "Ranking Points" (RPs)

Auto

Example: 2020 game - Infinite Recharge

| Award | Awarded for | AUTO | TELEOP | Qual. | |
|------------------------------------|---|------|---------|--------------------|--------|
| INITIATION LINE | exit the infinite vertical volume created by the corresponding ALLIANCE'S INITIATION LINE any time before the end of AUTO (per ROBOT) | 5 | - | - | |
| POWER CELLS | scored in BOTTOM PORT | 2 | 1 | - | |
| | scored in OUTER PORT | 4 | 2 | - | |
| | scored in INNER PORT | 6 | 3 | - | |
| CONTROL PANEL | ROTATION CONTROL | - | 10 | - | |
| | POSITION CONTROL | | 20 | 1 | |
| ENDGAME Points | HANG (per ROBOT) | - | 25 | - | |
| | PARK (per ROBOT) | - | 5 | - | |
| | LEVEL with 1-3 ROBOTS HANGING (per ALLIANCE) | | 15 | | |
| SHIELD GENERATOR OPERATIONAL | earning at least sixty-five (65) ENDGAME points | | | 1 Ranking Point | |
| SHIELD GENERATOR ENERGIZED | Stage 3 ACTIVATED | - | - | 1 Ranking Point | |
| Tie | Completing a MATCH with the same number of points as your opponent | - | - | 1 Ranking Point | |
| Win | Completing a MATCH with more points than your opponent | - | - | 2 Ranking Point | |
| Tele-op | | | Endgame | | Totals |

| | | Tele-op | | | | | Linganic | | | Totals | | | | | |
|---------|--------------------|-----------|----------|----------|-----------|----------|----------|-------------------|-------------------|-------------|------------|--------------|--------|----------------|--|
| L | Line Crossed (y/n) | Bottom PC | Outer PC | Inner PC | Bottom PC | Outer PC | Inner PC | CP Rotation (y/n) | CP Position (y/n) | Climb (y/n) | Park (y/n) | Level? (y/n) | Points | Alliance Total | |
| Robot 1 | у | 3 | 0 | 0 | 3 | 6 | 0 | | | | n | у | | 56 | |
| Robot 2 | у | 3 | 0 | 0 | 5 | 5 | 1 | у | n | у | n | у | 54 | 182 | |
| Robot 3 | у | 0 | 3 | 0 | 0 | 15 | 0 | | | у | n | | 72 | | |
| Robot 4 | у | 0 | 3 | 0 | 0 | 15 | 1 | | у | у | n | у | 120 | 274 | |
| Robot 5 | у | 0 | 3 | 0 | 0 | 20 | 0 | у | | у | n | | 82 | | |
| Robot 6 | у | 0 | 3 | 0 | 0 | 15 | 0 | | | у | n | | 72 | | |



Game Analysis: Robot Tasks and Skills

25 Hold Low Bar Flap Open

Example: 2016 game - Stronghold

List all of the skills that a robot \bullet needs to complete game tasks

- Scoring
- Navigating
- Defending?

| Robot Skills | Tasks | Auto | Teleop | Quals | Elims | Required Skills | Beneficial Skills |
|--|---------------------|------|--------|-------|-------|------------------------|--------------------------|
| 1 Drive | Reach Defense | 2 | | | | 1 | |
| 2 Drive over Small Bump | Cross Low Bar | 10 | 5 | | | 1,3,20 | |
| 3 Drive on ramp | Cross French Ramps | 10 | 5 | | | 1,3,16 | 17 |
| 4 Drive (Most Terrain) | Cross Portcullis | 10 | 5 | | | 1,3,15 | 14 |
| 5 Herd Boulder | Cross Moat | 10 | 5 | | | 1,3,4 | |
| 6 Hold Boulder | Cross Ramparts | 10 | 5 | | | 1,3,4 | |
| 7 Receive Boulder from Lower Wall Hole | Cross Drawbridge | 10 | 5 | | | 1,3,13 | 12 |
| 8 Receive Boulder from Upper Wall Hole | Cross Sally Door | 10 | 5 | | | 1,3,19 | 18 |
| 9 Pick Up Boulder | Cross Rough Terrain | 10 | 5 | | | 1,3,4 | |
| 10 Shoot Boulder | Cross Rock Wall | 10 | 5 | | | 1,3,4 | |
| 11 Relase Boulder | Boulder Top | 10 | 5 | | | 1,6,9,10 | 2,3,4,5,7,8,11 |
| 12 Hold Drawbridge for Others | Boulder Bottom | 5 | 2 | | | 1,2,3,5 | 4,6,7,8,9,11 |
| 13 Drop Drawbridge from Neutral | Climb Tower | | 15 | | | 1,2,3,21 | 4 |
| 14 Hold Portcullis for Others | Challenge Tower | | 5 | | | 1,2,3 | 4 |
| 15 Lift Portcullis | Capture Tower | | | 1RP | 25 | 1,2,3 | 4 |
| 16 Push Down French Ramps | Breach Defenses | | | 1RP | 20 | 1,2,3,4,13,15,16,19,20 | 12,13,15,17,18 |
| 17 Lift French Ramps for Others | | | | | | | |
| 18 Hold Sully Door for Others | | | | | | | |
| 19 Open Sully Door from Neutral | | | | | | | |
| 20 Limbo | | | | | | | |
| 21 Climb Tower | | | | | | | |
| 22 Defend | | | | | | | |
| 23 Dislodge Self | | | | | | | 11 |
| 24 Dislodge Others | | | | | | | 11 |



Game Analysis: Match Strategies

- How do you actually play the game?
 - A fun activity is playing a human game to compare different strategies

Typical Strategies:

- Shootout
 - Ignore the opponents and just score
- Counterplay
 - Use one or more robots to interrupt the other alliance's game plan
- Starvation
 - Deny the opposing alliance any opportunity to score
- Chokehold
 - Accomplish some set of tasks that makes it impossible to lose control
- Think about both your scoring potential and the *differential* to your opponents

Robot archetypes:

• Scorer

- Accomplish the "main" game task
- Supporter
 - Accomplish "side goals"
- Endgame/Bonus
 - \circ \qquad Get the "end game" or "bonus" points
- Defense
 - Prevent opponents from scoring 10 points is as good as you scoring 10 points
- Robots can be none to many of these



Game Analysis: Match Strategies

- You pick a general path, but maybe not a specific design right away
 - You should leave some questions open and use prototypes and outside data to answer them
- Be realistic
- Alliance compatibility
- Rules of thumb
 - Elite teams can do 8 full field cycles per match in perfect conditions
 - The best teams will do this a few times a season
 - Middle tier teams can do 4 cycles per match and average maybe 2-3





Game Analysis: Robot Concepts

- Start to scribble robot concepts
 - These should accomplish the match strategies you described
 - How do you combine "robot skills" into a full robot concept?
 - Think back to "Robot Points" how much complexity can you plan on?
 - Use anything to communicate
 - Whiteboards, MS Paint, block
 CAD, cardboard and hot glue
 - The details may come eventually





Robot Analysis: Gamepiece "Flow"

- How are different Robot Skills related?
 - How do different mechanisms rely on each other?
- Gamepiece "Flow"
 - How does a gamepiece get to the goal?
 - Where is the bottleneck?
 - It doesn't matter if the scorer is the best in the world if nothing gets to it
 - Examples
 - An intake feeds an indexer which feeds a scorer.
 - A claw is moved on an elevator to get to the scoring height



Design Selection Methods

Design Selection: Focusing Your Strategy

- Narrow down robot concepts based on goals and feasibility
 - 2-3 concepts to further analyze
- Think about how these robots will play the game in an alliance
 - Can the design be successful solo?
 - Is the design reliant on Alliance partners?
- List which game tasks are required for selected concepts
 - This will help prioritize robot functions
 - Drivetrain should almost always be a top priority (very few exceptions)

Design Selection: Tradeoffs + Priorities

- Mutually exclusive tradeoffs?
 - Speed vs power
 - Complexity vs durability
 - Wide vs long frame
 - High vs low center of gravity (easier shot vs tippy robot)
- Prioritization of complexity
 - Time spent on
 - Design, Build, Program, Test, Practice, Iterate, Compete, Repeat
 - Use your strategic priorities to decide the design process
 - Which mechanism do we focus on first?



Design Selection: Wait and try it?

There's only so much that you can talk about around a table

- Some decisions have to be informed by prototyping and testing
 - Which material works best for this gamepiece?
 - How hard is it to pick this up off the carpet?
- If different design paths depend on radically different mechanisms, can you use testing to focus on a better option?
 - If a game involves scoring balls in a high goal (2020, 2017, 2016, 2014...) and you're considering multiple launchers (flywheel, catapult, puncher...) maybe testing will eliminate one early on



Design Selection: Wait and copy?

Steal from the best.

- Check past games!
 - If a game has a horizontal pull-up bar, what did teams do in 2020, 2018, 2016, 2013...
 - "Ok cool, telescoping or unfolding arms, not a grappling hook."
- Are there any teams around you or online who want to work together or show ideas?
 - Teams are a different mix of "Open" or "Secret"
 - #Openalliance on Chiefdelphi
 - "Robot in 3 days"
 - Everybot
 - Literally, just search YouTube



Design Selection: Feature Ramp

- How much can you work on at a time?
 - What's most important?
 - Drivetrain > Endgame > Main Scoring > Secondary Scoring?
 - Block out space for a mechanism, ignore it, and get back to it later
- What features matter when?
 - The level of play will get better. You only have to beat the teams at your event!
- Examples:
 - 2020 color wheel
 - 2019 panel vs cargo
 - 2016 low goal
 - More advanced autonomous



Design Selection: Making a Decision

- It shouldn't be an argument
 - Data from analysis, prototypes and other teams should make it a more objective conversation
- When things escalate:
 - Decision matrix?
 - More testing? Prove it.
 - Don't get attached to your own idea/prototype
 - "A good plan violently executed now is better than a perfect plan executed next week."
 - Also, it won't be perfect next week...
 - IF it comes down to voting, someone will always walk away mad.

Example Season



Example: 2017 Steamworks, Team 1732

- Goals:
 - \circ Win a Regional and be competitive at Champs
- Resources:
 - \circ Budget for practice bot
 - Drillpress/bandsaw machining (no CNC)
 - Local practice field (Thanks Robotigers 2830!)
- Game analysis + priorities
 - 1. Gear scoring + Climbing
 - 2. Drive practice
 - 3. Ball scoring
 - 4. Additional autonomous routines
- Feature Ramp-up:
 - Regional 1: Gear scoring, climbing
 - \circ $\hfill Regional 2:$ Practice ball scoring, but play to win
 - Champs: Faster climbing, faster ball scoring
 - Offseason: Moved climber up for faster climb



Resources

- Old games
 - Rules/videos
 - https://www.firstinspires.org/resource-library/frc/archived-game-documentation
 - Match footage
 - https://www.thebluealliance.com/
- Effective FIRST Strategies-Karthik Kanagasabapathy
 - <u>https://www.youtube.com/watch?v=xJYv7uxXMn0</u>
- Goal Setting- Mike Corsetto
 - <u>https://www.youtube.com/watch?v=TyBWSDEIuXI</u>
- Simple Thinking- Adam Heard
 - <u>https://www.youtube.com/watch?v=JyPHwNx_KXM</u>



Questions?

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